

Fast determination of the tensorial and simplicial Bernstein enclosures

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Jihad Titi

Jürgen Garloff

University of Konstanz

Department of Mathematics and Statistics

and

University of Applied Sciences / HTWG Konstanz

Institute of Applied Research

Outline

- The tensorial Bernstein form of a multivariate polynomial
 - ◇ Properties
 - ◇ Computation of the tensorial Bernstein coefficients over the unit and a general box
 - ★ Existing methods
 - ★ New methods
 - ◇ Computation of the Bernstein coefficients over sub-boxes generated by subdivision
- The simplicial Bernstein form of a multivariate polynomial
- Related work

Notation

- Let n be the number of variables.
- A multi-index $(i_1, \dots, i_n) \in \mathbb{N}^n$ is abbreviated by i . In particular, we write 0 for $(0, \dots, 0)$.
- Comparison between and arithmetic operations with multi-indices are defined entry-wise. For $x = (x_1, \dots, x_n) \in \mathbb{R}^n$, its *monomials* are defined as $x^i := \prod_{s=1}^n x_s^{i_s}$.
- For $d = (d_1, \dots, d_n) \in \mathbb{N}^n$, we use the compact notations
 - ◇ $\sum_{i=0}^d := \sum_{i_1=0}^{d_1} \cdots \sum_{i_n=0}^{d_n}$
 - ◇ $\binom{d}{i} := \prod_{s=1}^n \binom{d_s}{i_s}$.

Tensorial Bernstein form

- Let p be an n -variate polynomial of degree l at most

$$p(x) = \sum_{i=0}^l a_i x^i.$$

- The i -th Bernstein polynomial of degree d , $d \geq l$, over $\mathbf{u} = [0, 1]^n$ is the polynomial ($0 \leq i \leq d$)

$$B_i^{(d)}(x) = \binom{d}{i} x^i (1-x)^{d-i}.$$

- The Bernstein polynomials of degree d (over \mathbf{u}) form a basis of the vector space of the polynomials of degree at most d . Therefore, p can be represented by

$$p(x) = \sum_{i=0}^d b_i^{(d)} B_i^{(d)}(x), \quad d \geq l.$$

- The coefficients of this expansion are given by ($a_j := 0$ for $j \geq l$ and $j \neq l$)

$$b_i^{(d)} = \sum_{j=0}^i \frac{\binom{i}{j}}{\binom{d}{j}} a_j, \quad 0 \leq i \leq d.$$

(*Bernstein coefficients*).

- The Bernstein coefficients can be arranged in a multidimensional array $B(\mathbf{u}) = (b_i^{(d)})_{0 \leq i \leq d}$, the so-called *Bernstein patch*.

Properties of the Bernstein coefficients

- **Endpoint interpolation property (vertex values):** If

$i_s \in \{0, l_s\}$, $s = 1, \dots, n$, then $b_i = p(v)$, where

$$v_s = \begin{cases} 0, & i_s = 0, \\ 1, & i_s = l_s, \end{cases} \text{ for all } s = 1, \dots, n.$$

- **Linearity :** Let $p = \alpha p_1 + \beta p_2$, $\alpha, \beta \in \mathbb{R}$, where l is the maximum degree of p_1 and p_2 . Then

$$b_i^{(d)}(p) = \alpha b_i^{(d)}(p_1) + \beta b_i^{(d)}(p_2), \text{ for all } 0 \leq i \leq d,$$

where $b_i^{(d)}(p_1)$ and $b_i^{(d)}(p_2)$ are the i -th coefficients of the degree d of the Bernstein expansions of p_1 and p_2 , respectively, $d \geq l$.

- The Bernstein polynomials of degree d (over \mathbf{u}) form a basis of the vector space of the polynomials of degree at most d . Therefore, p can be represented by

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- The coefficients of this expansion are given by ($a_j := 0$ for $j \geq l$ and $j \neq l$)

$$b_i^{(d)} = \sum_{j=0}^i \frac{\binom{i}{j}}{\binom{d}{j}} a_j, \quad 0 \leq i \leq d.$$

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- **Convex hull property:** The graph of p over \mathbf{u} is contained in the convex hull of the control points :

$$\left\{ \begin{pmatrix} x \\ p(x) \end{pmatrix} : x \in \mathbf{u} \right\} \subseteq \text{conv} \left\{ \begin{pmatrix} i/d \\ b_i \end{pmatrix} : 0 \leq i \leq d \right\}.$$

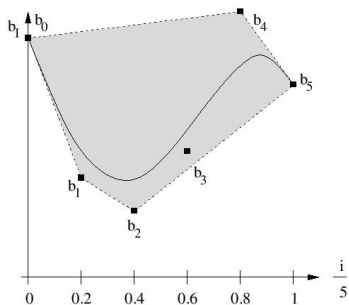


Figure: The graph of a degree 5 polynomial and the convex hull (shaded) of its control points (marked by squares).

- **Range enclosing property** : For all $x \in \mathbf{u}$

$$\min_{i=0}^d b_i^{(d)} \leq p(x) \leq \max_{i=0}^d b_i^{(d)}. \quad (1)$$

Equality holds in the left or right inequality in (1) if and only if the minimum or the maximum, respectively, is attained at a vertex of \mathbf{u} . This property is called **the sharpness (vertex) property**.

- **Inclusion isotonicity** : If the unit box \mathbf{u} shrinks then the Bernstein enclosure shrinks, too.

Improvements of the range enclosure

- **Degree elevation:** The Bernstein coefficients $b_i^{(d+1)}$ of p over \mathbf{u} can be obtained from the Bernstein coefficients $b_i^{(d)}$ as follows

$$b_i^{(d+1)} = \frac{ib_{i_s, -1}^{(d)} + (d+1-i)b_i^{(d)}}{d+1}, i = 0, \dots, d+1,$$

with $b_{-1}^{(d)} = b_{d+1}^{(d)} = 0$.

- **Tensorial subdivision:** Subdivision of \mathbf{u} in the s -th coordinate direction, $s \in \{1, \dots, n\}$, produces two subboxes \mathbf{u}_1 and \mathbf{u}_2 ,

$$\begin{aligned}\mathbf{u}_1 &:= [0, 1] \times \dots \times [0, \lambda] \times \dots \times [0, 1], \\ \mathbf{u}_2 &:= [0, 1] \times \dots \times [\lambda, 1] \times \dots \times [0, 1],\end{aligned}$$

for some $\lambda \in (0, 1)$.

The Bernstein coefficients over \mathbf{u}_1 and \mathbf{u}_2 , denoted by $b_i(\mathbf{u}_1)$ and $b_i(\mathbf{u}_2)$, respectively, can be computed from the Bernstein coefficients b_i over \mathbf{u} by using the de Casteljau algorithm.

- **Subdivision** is more efficient than degree elevation since iteratively applied subdivision generates a sequence of enclosures which **converges quadratically** to the range of p over \mathbf{u} , in contrast to **linear convergence** when **degree elevation** is applied.

Computation of the tensorial Bernstein coefficients over the unit and a general box

- Existing methods
 - ★ difference table method (G., 1986)
 - ★ Ray and Nataraj's method (matrical method 2012)
- New methods

Difference table method

- The Bernstein coefficients of a bivariate polynomial p of degree (l_1, l_2) over \mathbf{u} are related to the coefficients of p by a forward difference operator Δ

$$\Delta_{j_1, j_2} b_0 = \frac{1}{\binom{l_1}{j_1} \binom{l_2}{j_2}} a_{j_1, j_2}.$$

- The Bernstein coefficients can be computed by the following recurrence relations :

$$\begin{aligned}\Delta_{00} b_{i_1, i_2} &= b_{i_1, i_2}, \\ \Delta_{j_1+1, j_2} b_{i_1, i_2} &= \Delta_{j_1, j_2} b_{i_1, i_2} - \Delta_{j_1, j_2} b_{i_1+1, i_2}, \\ \Delta_{j_1, j_2+1} b_{i_1, i_2} &= \Delta_{j_1, j_2} b_{i_1, i_2} - \Delta_{j_1, j_2} b_{i_1, i_2+1},\end{aligned}$$

where $0 \leq i_1 + 1 \leq l_1$, $0 \leq i_2 + 1 \leq l_2$, and $\Delta_{j_1, j_2} b_{0,0} := 0$ if $j_1 > l_1$ or $j_2 > l_2$.

Ray and Nataraj's method

- Ray and Nataraj proposed a matrix method for computing the Bernstein coefficients of a multivariate polynomial over the unit and a general box.
- Their method involves only matrix operations such as multiplication, inversion, transposition, and reshaping.
- The method is obtained by equating the matrix representations of a polynomial in power form and in Bernstein form and solving for the Bernstein coefficients.

New methods

We propose a method for the computation of the Bernstein coefficients of a given multivariate polynomial over the unit box and a general box which is **superior to the two former methods**.

Matrix methods over the unit box

- Bivariate case

- ◇ Matrical description of difference table method

We start by arranging the coefficients of p in a matrix A as follows :

$$A = \begin{bmatrix} a_{0,0} & a_{0,1} & \dots & a_{0,l_2} \\ a_{1,0} & a_{1,1} & \dots & a_{1,l_2} \\ \vdots & \vdots & \dots & \vdots \\ a_{l_1,0} & a_{l_1,1} & \dots & a_{l_1,l_2} \end{bmatrix} .$$

◇ Let the entries of the matrix $\Lambda(\mathbf{u}) = (\lambda_{j_1, j_2})$ be given by

$$\lambda_{j_1, j_2} := \frac{a_{j_1-1, j_2-1}}{\binom{l_1}{j_1-1} \binom{l_2}{j_2-1}}, \text{ where } j_s = 1, \dots, l_s + 1, s = 1, 2.$$

◇ Starting from row $l_s - \mu + 2$, addition of each row to the following one, $\mu = 1, \dots, l_s$, is described by left multiplication by the matrices

$$K_\mu^s := \begin{bmatrix} 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 1 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 1 & 1 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \leftarrow l_s - \mu + 2$$

Then the Bernstein patch is given as

$$B(\mathbf{u}) = (K_1^2 \cdots K_{l_2}^2 (K_1^1 \cdots K_{l_1}^1 \Lambda(\mathbf{u}))^T)^T.$$

For the *lower triangular Pascal matrix*

$$P_s := \begin{bmatrix} \binom{0}{0} & 0 & \dots & 0 \\ \binom{1}{0} & \binom{1}{1} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \binom{l_s}{0} & \binom{l_s}{1} & \dots & \binom{l_s}{l_s} \end{bmatrix}$$

the factorization

$$P_s = \prod_{\mu=1}^{l_s} K_{\mu}^s$$

holds. Therefore,

$$B(\mathbf{u}) = (P_2(P_1\Lambda(\mathbf{u}))^T)^T.$$

- Multivariate case

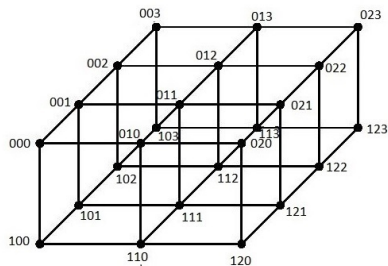
- ◇ Let p be an n -variate polynomial of degree $l = (l_1, \dots, l_n)$.
- ◇ The coefficients of p are arranged in an $(l_1 + 1) \times l^*$ matrix, where $l^* := \prod_{i=2}^n (l_i + 1)$, as follows

$$\begin{bmatrix}
 a_{0,0,0,\dots,0} & a_{0,1,0,\dots,0} & \dots & a_{0,l_2,0,\dots,0} & \dots & a_{0,0,l_3,\dots,0} & a_{0,1,l_3,\dots,0} & \dots & a_{0,l_2,l_3,\dots,l_n} \\
 a_{1,0,0,\dots,0} & a_{1,1,0,\dots,0} & \dots & a_{1,l_2,0,\dots,0} & \dots & a_{1,0,l_3,\dots,0} & a_{1,1,l_3,\dots,0} & \dots & a_{1,l_2,l_3,\dots,l_n} \\
 \vdots & \vdots & \dots & \vdots & \dots & \vdots & \vdots & \dots & \vdots \\
 a_{l_1,0,0,\dots,0} & a_{l_1,1,0,\dots,0} & \dots & a_{l_1,l_2,0,\dots,0} & \dots & a_{l_1,0,l_3,\dots,0} & a_{l_1,1,l_3,\dots,0} & \dots & a_{l_1,l_2,l_3,\dots,l_n}
 \end{bmatrix}$$

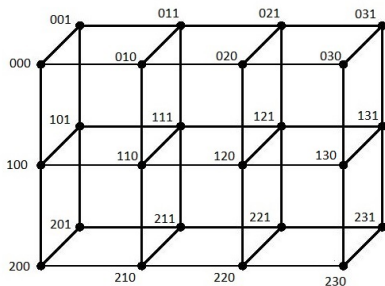
- ◇ The superscript c denotes the *cyclic ordering* of the sequence of the indices.

Cyclic ordering for a three-dimensional array with

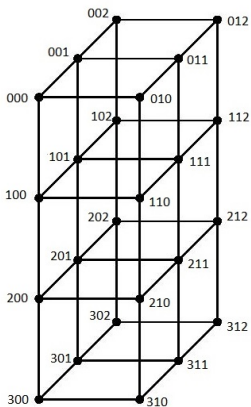
$$l_1 = 1, l_2 = 2, l_3 = 3$$



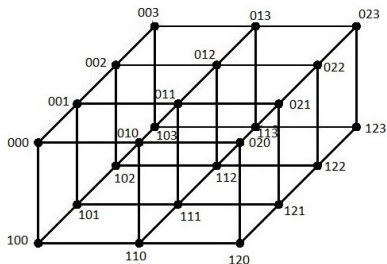
(a) $\Lambda(\mathbf{u})$



(b) $(P_1\Lambda(\mathbf{u}))^c$



(c) $(P_2(P_1\Lambda(\mathbf{u}))^c)^c$



(d) $(P_3(P_2(P_1\Lambda(\mathbf{u}))^c)^c)^c$ providing $B(\mathbf{u})$

- ◇ The matrix $\Lambda(\mathbf{u})$ is obtained from A by multiplying a_{i_1, \dots, i_n} by $\binom{l_1}{i_1}^{-1} \cdots \binom{l_n}{i_n}^{-1}$.
- ◇ We put

$$\begin{aligned}\Lambda_0 &:= \Lambda(\mathbf{u}), \\ \Lambda_s &:= (P_s \Lambda_{s-1}(\mathbf{u}))^c, \quad s = 1, \dots, n.\end{aligned}$$

- ◇ The Bernstein patch $B(\mathbf{u})$ arranged accordingly in an $(l_1 + 1) \times l^*$ matrix is given by Λ_n .

Matrix methods for a general box

- ★ We affinely map a given box $\mathbf{x} = [\underline{x}_1, \bar{x}_1] \times \cdots \times [\underline{x}_n, \bar{x}_n]$ to \mathbf{u} by

$$z_s = \frac{x_s - \underline{x}_s}{\bar{x}_s - \underline{x}_s}, \quad s = 1, \dots, n. \quad (2)$$

- ★ With $D_s(t) := \text{diag}(1, t, t^2, \dots, t^k)$ put

$$Q_s := \begin{cases} D_s\left(\frac{\bar{x}_s - \underline{x}_s}{x_s}\right) P_s^T D_s(\underline{x}_s), & \underline{x}_s \neq 0, \\ D_s(\bar{x}_s), & \underline{x}_s = 0. \end{cases}$$

- ★ After substituting (2) in p we obtain a polynomial p^* over \mathbf{u} . The coefficients of p^* are arranged in a matrix, A^* say, which is given by

$$A^* = (Q_n(\dots(Q_2(Q_1 A)^c)\dots)^c)^c.$$

- ★ Then apply the procedure for the unit box to A^* .

Amount of arithmetic operations

Unit box

- For simplicity and ease of comparison between the existing methods, we assume that $l_1 = \dots = l_n = \kappa$.
- Some basic quantities like factorials and binomial coefficients are precomputed.
- We present two new methods together with their complexity by which we can carry out the matrix multiplication in

$$\Lambda_n = (P_n(\dots(P_2(P_1\Lambda(\mathbf{u}))^c)^c \dots)^c)^c.$$

Method 1

- We use the factorization

$$P = K_1 K_2 \cdots K_\kappa.$$

This factorization allows us to get rid of the multiplication operations.

- Method 1 is superior to method (R.N) if $\kappa > 1$ (the complexity of both methods is $O(n\kappa^{n+1})$).

TABLE – Comparison between the number of arithmetic operations of the three methods

Method	number of additions	number of multiplications/divisions
R.N	$n \frac{\kappa(\kappa+1)^n}{2}$	$\frac{\kappa(\kappa-1)}{2} + n \frac{\kappa(\kappa+1)^n}{2}$
Method 1 and difference table method	$n \frac{\kappa(\kappa+1)^n}{2}$	$n(\kappa + 1)^n$

Method 2

- We use the factorization

$$P = GTG^{-1},$$

where $G := \text{diag}(1, 1, 2!, \dots, \kappa!)$ and T is the lower triangular Toeplitz matrix

$$T := \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & 0 \\ 1 & 1 & 0 & \dots & 0 & 0 \\ \frac{1}{2!} & 1 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \frac{1}{(\kappa-1)!} & \frac{1}{(\kappa-2)!} & \frac{1}{(\kappa-3)!} & \dots & 1 & 0 \\ \frac{1}{\kappa!} & \frac{1}{(\kappa-1)!} & \frac{1}{(\kappa-2)!} & \dots & 1 & 1 \end{bmatrix}.$$

- The factorials $i_\varrho!$ appearing in $\binom{\kappa}{i_\varrho}^{-1}$ and on the diagonal of G^{-1} cancel out, $\varrho = 1, \dots, n$.
- Multiply a_{i_1, \dots, i_n} by $\frac{(\kappa - i_1)!}{\kappa!} \dots \frac{(\kappa - i_n)!}{\kappa!}$ and name the resulting matrix $\Lambda'(\mathbf{u})$ then

$$\underbrace{(GT(\dots(GT(GT\Lambda'(\mathbf{u}))^c)^c \dots)^c)^c}_{n \text{ times}}$$

gives the Bernstein patch in matrix form.

- The computation of the matrix-vector multiplication with the matrix T can be carried out by using the **Fast Fourier Transform (FFT)**.
- Then the total number of operations required for the computation of $B(\mathbf{u})$ can be reduced to $O(n\kappa^n \log_2 \kappa)$, whereas the complexity of Method 1 is $O(n\kappa^{n+1})$, so Method 2 has lowest complexity.

General box

Method 1

TABLE – Number of arithmetic operations required to obtain the Bernstein patch over a general box by (Method 1) and (R.N)

Calculation of	number of additions	number of multiplications/divisions
$D(x_s), D(\frac{\bar{x}_s - x_s}{x_s})$	n	$2n(\kappa - 1) + n$
A^*	$n\kappa \frac{(\kappa+1)^n}{2}$	$2n(\kappa + 1)^n$
Method 1 over u (starting from A^*)	$n\kappa \frac{(\kappa+1)^n}{2}$	$n(\kappa + 1)^n$
total number of Method 1	$n\kappa(\kappa + 1)^n + n$	$3n(\kappa + 1)^n + 2n(\kappa - 1) + n$
R.N	$\frac{n + n\kappa(\kappa+1)(2\kappa+1)}{6} + n\kappa(\kappa + 1)^n$	$\frac{\kappa(\kappa-1)}{2} + \kappa n(\kappa + 3) + \frac{n(\kappa+1)(\kappa+2)(2\kappa+3)}{6} + n(\kappa + 1)^{n+1}$

The complexity of Method 1 and (R.N) is $O(n\kappa^{n+1})$ but Method 1 is superior for $\kappa > 1$.

Tensorial subdivision

The Bernstein coefficients over the two sub-boxes \mathbf{u}_1 and \mathbf{u}_2 resulting from subdivision of the original box \mathbf{u} in the s -th direction, $s \in \{1, 2, \dots, n\}$, are obtained from the de Casteljau algorithm :

1. Put $b_i^{[0]} := b_i$, $0 \leq i \leq l$.
2. For $\nu = 1, \dots, l_s$:

$$b_i^{[\nu]} := \left\{ \begin{array}{ll} b_i^{[\nu-1]}, & \text{if } i_s < \nu \\ (1 - \lambda)b_{i_1, \dots, i_s-1, \dots, i_n}^{[\nu-1]} + \lambda b_i^{[\nu-1]}, & \text{if } i_s \geq \nu \end{array} \right\}, \quad 0 \leq i \leq l.$$

3. $b_i(\mathbf{u}_1) := b_i^{[l_s]}$; $b_i(\mathbf{u}_2) := b_{i_1, \dots, i_s-1, \dots, i_n}^{[l_s-i_s]}$, $0 \leq i \leq l$.

The Bernstein coefficients $b_i(\mathbf{u}_2)$ on the sub-box \mathbf{u}_2 are obtained as intermediate values of this computation, since for $\nu = 0, \dots, l_s$ the following relation holds $b_{i_1, \dots, i_s-\nu, \dots, i_n}(\mathbf{u}_2) = b_{i_1, \dots, i_s, \dots, i_n}^{[\nu]}(\mathbf{u})$.

Tensorial subdivision in matrix form

The Bernstein coefficients over the two sub-boxes \mathbf{u}_1 and \mathbf{u}_2 are arranged in matrices $\mathcal{B}(\mathbf{u}_1)$ and $\mathcal{B}(\mathbf{u}_2)$.

From the de Casteljau algorithm, we obtain $l_s + 1$ matrices. In the ν -th step, $\mathcal{B}^{[\nu]}(\mathbf{u})$ is given as follows:

The first ν rows are identical with the first ν rows in the $(\nu - 1)$ -th step and the remaining rows are obtained as a convex combination of two consecutive rows.

The Bernstein patch $\mathcal{B}(\mathbf{u}_1)$ over the sub-box \mathbf{u}_1 is provided by the last matrix $\mathcal{B}^{[l_s]}(\mathbf{u})$.

The i -th row, $i = 1, \dots, l_s + 1$, of the Bernstein coefficients matrix $\mathcal{B}(\mathbf{u}_2)$ over the sub-box \mathbf{u}_2 is equal to the last row in $\mathcal{B}^{[l_s - i + 1]}(\mathbf{u})$.

Without loss of generality we subdivide \mathbf{u} in the direction along the first coordinate direction ($s = 1$); the subdivision in the other directions is done by firstly considering the cyclic ordering.

- In matrix language, these manipulations are described by pre-multiplication of the matrix $\mathcal{B}(\mathbf{u})$ by the following matrices.
- For simplicity we assume that $l_1 = \dots = l_n = \kappa$.
- For $\mu = 1, 2, \dots, \kappa$ we define the matrices L_μ and $R_\mu \in \mathbb{R}^{\kappa+1, \kappa+1}$

$$L_\mu := \begin{bmatrix} 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & 1 - \lambda & \lambda & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 1 - \lambda & \lambda & \dots & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & 0 & 0 & 1 - \lambda & \lambda \end{bmatrix} \leftarrow l_s - \mu + 2$$

and

$$R_\mu := \begin{bmatrix} 1-\lambda & \lambda & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 \\ 0 & 1-\lambda & \lambda & \cdots & 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots & \vdots & \vdots & \cdots & \vdots \\ 0 & 0 & 0 & \cdots & 1-\lambda & \lambda & 0 & \cdots & 0 \\ 0 & 0 & 0 & \cdots & 0 & 1 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \leftarrow \mu + 1$$

- Then we obtain the Bernstein patches over \mathbf{u}_1 and \mathbf{u}_2 by

$$\begin{aligned} \mathcal{B}(\mathbf{u}_1) &= L_1 L_2 \dots L_\kappa \mathcal{B}(\mathbf{u}), \\ \mathcal{B}(\mathbf{u}_2) &= R_1 R_2 \dots R_\kappa \mathcal{B}(\mathbf{u}). \end{aligned}$$

- We define $L^\dagger \in \mathbb{R}^{\kappa+1, \kappa+1}$ by

$$L^\dagger := \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 - \lambda & \binom{1}{1}\lambda & 0 & \dots & 0 \\ (1 - \lambda)^2 & \binom{2}{1}(1 - \lambda)\lambda & \binom{2}{2}\lambda^2 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ (1 - \lambda)^\kappa & \binom{\kappa}{1}(1 - \lambda)^{\kappa-1}\lambda & \binom{\kappa}{2}(1 - \lambda)^{\kappa-2}\lambda^2 & \dots & \binom{\kappa}{\kappa}\lambda^\kappa \end{bmatrix}.$$

- We have the factorization

$$L^\dagger = \prod_{\mu=1}^{\kappa} L_\mu = D(1 - \lambda)PD\left(\frac{\lambda}{1 - \lambda}\right).$$

- Then $\mathcal{B}(\mathbf{u}_1)$ can be represented as

$$\mathcal{B}(\mathbf{u}_1) = D(1 - \lambda)PD\left(\frac{\lambda}{1 - \lambda}\right)\mathcal{B}(\mathbf{u}).$$

- By using $P = GTG^{-1}$, we have

$$\mathcal{B}(\mathbf{u}_1) = D^{(2)}TD^{(1)}\mathcal{B}(\mathbf{u}),$$

where $D^{(2)} := D(1 - \lambda)G$ and $D^{(1)} := G^{-1}D\left(\frac{\lambda}{1-\lambda}\right)$.

- In the same way $\mathcal{B}(\mathbf{u}_2)$ can be obtained.

TABLE – Comparison between the de Casteljau algorithm and the proposed method for the computation of $\mathcal{B}(\mathbf{u}_1)$ and $\mathcal{B}(\mathbf{u}_2)$

Calculation of	number of additions	number of multiplications/ divisions
de Casteljau algorithm	$\kappa \frac{(\kappa+1)^n}{2}$	$\kappa(\kappa+1)^n$
$\mathcal{B}(\mathbf{u}_1)$	$\kappa \frac{(\kappa+1)^n}{2}$	$2\kappa(\kappa+1)^{n-1} + 2\kappa$
$\mathcal{B}(\mathbf{u}_2)$	$\kappa \frac{(\kappa+1)^n}{2}$	$(\kappa+1)^{n-1}(2\kappa+1) + 3\kappa$
$\mathcal{B}(\mathbf{u}_1)$ and $\mathcal{B}(\mathbf{u}_2)$ together	$\kappa^2(\kappa+1)^{n-1}$	$3\kappa(\kappa+1)^{n-1} + 4\kappa$

J. Titi and J. Garloff, Matrix Methods for the Tensorial Bernstein Form and for the Evaluation of Multivariate Polynomials, submitted.

The simplicial Bernstein form

- Let v_0, v_1, \dots, v_n be $n + 1$ affinely independent points of \mathbb{R}^n . Their convex hull is called *simplex of vertices* v_0, v_1, \dots, v_n and denoted by $V = [v_0, v_1, \dots, v_n]$.
- Any vector $x \in \mathbb{R}^n$ can be written as an affine combination of the vertices v_0, v_1, \dots, v_n with weights $\lambda_0, \dots, \lambda_n$ called *barycentric coordinates*.
- If $x = (x_1, \dots, x_n) \in V$, then $\lambda = (\lambda_0, \dots, \lambda_n) = (1 - \sum_{i=1}^n x_i, x_1, \dots, x_n)$.
- For every multi-index $\alpha = (\alpha_0, \dots, \alpha_n) \in \mathbb{N}^{n+1}$ we put $\hat{\alpha} := (\alpha_1, \dots, \alpha_n)$ and we write $|\alpha| := \alpha_0 + \dots + \alpha_n$.

The simplicial Bernstein form

- If $|\alpha| = k$, we further use the notation $\binom{k}{\alpha} := \frac{k!}{\alpha_0! \dots \alpha_n!}$.
- We will consider here only the *standard simplex* $\Delta := [0, e_1, \dots, e_n]$, where e_s is the s^{th} vector of the canonical basis of \mathbb{R}^n , $s = 1, \dots, n$. This is no restriction since any non-degenerate simplex V in \mathbb{R}^n can be mapped affinely upon Δ .
- **Results :**
Matrix methods for the computation of the Bernstein coefficients and of the Bernstein coefficients on subsimplices generated by bisection of Δ .

- Bernstein polynomials of degree k over Δ are the polynomials $(B_\alpha^{(k)})_{|\alpha|=k}$, defined as

$$B_\alpha^{(k)} := \binom{k}{\alpha} \lambda^\alpha.$$

- The Bernstein polynomials of degree k form a basis of the vector space of polynomials of degree at most k . Therefore, p can be uniquely represented as

$$p(x) = \sum_{|\alpha|=k} b_\alpha^{(k)} B_\alpha^{(k)}.$$

- The coefficients of this expansion are given by

$$b_\alpha^{(k)} = \sum_{\hat{\beta} \leq \hat{\alpha}} \frac{\binom{\hat{\alpha}}{\hat{\beta}}}{\binom{k}{\beta}} a_{\hat{\beta}}, \quad a_{\hat{\beta}} := 0 \text{ for } \hat{\beta} \geq l, \hat{\beta} \neq l.$$

(Bernstein coefficients)

Related work

- Computation (without overestimation) of the set of all tensorial Bernstein coefficients of an interval polynomial
- Matrix methods for the evaluation of multivariate polynomial in the
 - ◇ power representation (Horner scheme)
 - ◇ tensorial Bernstein representation
 - ◇ simplicial Bernstein representation

THANK YOU VERY MUCH